

# Maximum Likelihood Estimation for Semiparametric Regression Models with Interval-Censored Multi-State Data

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March 20, 2023

# Acknowledgments

- Dr. Donglin Zeng
- Dr. Gerardo Heiss
- Dr. Danyu Lin



Gu, Y., Zeng, D., Heiss, G., Lin, D. Y. Maximum Likelihood Estimation for Semiparametric Regression Models with Interval-Censored Multi-State Data. <https://arxiv.org/abs/2209.07708>.

# Outline

- 1 Introduction
- 2 Methods
- 3 Simulation Studies
- 4 Application

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1 Introduction

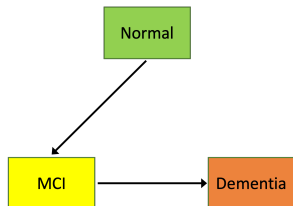
2 Methods

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# Multi-State Data

- Multi-state data arise frequently in studies of chronic diseases (e.g., dementia, cancer).
- Health status can be characterized by a finite number of disease states.
- **Transition**: change from one state to another



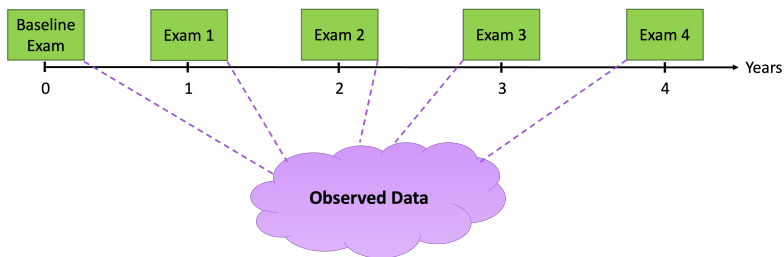
# Significance

Analysis of multi-state data allows us to

- understand how a subject transitions from one state to another over time
- study the associations between risk factors and the disease process
- predict disease progression over time

# Interval Censoring

- For economic and logistical reasons, subjects can only be examined periodically, such that transitions are only known to occur between two successive examinations.



- Such data are called *interval-censored multi-state data*.

# Analysis Challenges

- None of the transition times are directly observed.
- Trajectory of transitions from one examination to the next is unknown.
- Dependence among transitions of the same subject.



# Existing Methods

- Nonhomogeneous*
- ## Time-homogeneous Markov models
- ▶ Kalbfleisch & Lawless (1985); Satten (1999); Cook et al. (2002, 2004)
  - ▶ simple; parametric; implemented in the `msm` package
  - ▶ homogeneous assumption is unrealistic
- Nonparametric*
- ## Piecewise constant transition intensities
- ▶ Gentleman et al. (1994); Saint-Pierre et al. (2003); Jackson (2011); Lawless & Nazeri Rad (2015)
  - ▶ relatively simple; parametric
  - ▶ restrictive; sensitive to the choice of change points
- ## Spline-based intensities + penalized likelihood
- ▶ Joly & Commenges (1999); Machado & van den Hout (2018); Machado et al. (2021)
  - ▶ more flexible; semiparametric
  - ▶ tuning parameters (e.g., knots); inconsistent estimators

# Overview of this work

- We provide a new framework to study semiparametric regression models for general interval-censored multi-state data.
- Our models use random effects to capture the dependence among transitions and accommodate time-dependent covariates.
- We adopt *nonparametric maximum likelihood estimation* (NPMLE) for inference.
- We devise a stable EM algorithm to compute the estimators.

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# Semiparametric Regression Model

We specify the following proportional intensity model:

$$\lambda_{ijk}(t; \mathbf{X}_i, \mathbf{b}_i) = \lambda_{jk}(t) \exp \left\{ \boldsymbol{\beta}_{jk}^\top \mathbf{X}_i(t) + \mathbf{b}_i^\top \mathbf{Z}_i(t) \right\} \quad (1)$$

- $\lambda_{jk}(\cdot)$ : arbitrary baseline intensity function
- $\boldsymbol{\beta}_{jk}$ : unknown regression parameters
- $\mathbf{X}_i(\cdot)$ : potentially time-dependent covariates
- $\mathbf{b}_i \sim N_d(\mathbf{0}, \boldsymbol{\Sigma}(\gamma))$ : random effects
- $\mathbf{Z}_i(\cdot)$ : consists of 1 and covariates that are part of  $\mathbf{X}_i(\cdot)$

# Observed Data

- Examination times:  $(U_{i0}, U_{i1}, \dots, U_{iM_i})$
- Observed states:  $(S_{i0}, S_{i1}, \dots, S_{iM_i})$
- Covariates:  $\mathbf{X}_i(t)$

# Likelihood

Under the noninformative censoring and conditional Markov assumptions, the likelihood is proportional to

$$\prod_{i=1}^n \int \prod_{l=1}^{M_i} \mathbf{P}(U_{i,l-1}, U_{il}; \mathbf{X}_i, \mathbf{b}_i)^{(S_{i,l-1}, S_{il})} \phi(\mathbf{b}_i; \gamma) d\mathbf{b}_i \quad (2)$$

- $\mathbf{P}(u, v; \mathbf{X}_i, \mathbf{b}_i)$  denotes the transition probability matrix between times  $u$  and  $v$  for the  $i$ th subject.
- $\phi(\mathbf{b}; \gamma)$  denotes the density function of  $N_d(\mathbf{0}, \boldsymbol{\Sigma}(\gamma))$ .

# Compute Transition Probability

- The transition probability matrix is given by

$$\mathbf{P}(u, v; \mathbf{X}_i, \mathbf{b}_i) = \mathcal{T}_{u < t \leq v} \{ \mathbf{I}_K + d\mathbf{A}(t; \mathbf{X}_i, \mathbf{b}_i) \}$$

- $\mathbf{A}(t; \mathbf{X}_i, \mathbf{b}_i)$  is the cumulative transition intensity matrix, with

$$\mathbf{A}(t; \mathbf{X}_i, \mathbf{b}_i)^{(j,k)} = \int_0^t \exp\{ \boldsymbol{\beta}_{jk}^T \mathbf{X}_i(s) + \mathbf{b}_i^T \mathbf{Z}_i(s) \} d\Lambda_{jk}(s).$$

- $\Lambda_{jk}(t) = \int_0^t \lambda_{jk}(s) ds.$

# NPMLE

- We treat  $\Lambda_{jk}$  as step functions with nonnegative jumps at all examination times.
- Then the transition probability matrix

$$P_i(u, v) = \prod_{u < t \leq v} \{I_K + d\mathbf{A}_i(t)\}$$



$$\tilde{P}_i(u, v) = \prod_{u < t_q \leq v} \{I_K + \delta\mathbf{A}_i(t_q)\}.$$

- $\delta\mathbf{A}_i(t_q)$  involves the jump sizes  $\lambda_{jkq}$ , which are **high-dimensional and lack analytical expressions**.



# Poissonization

- We introduce independent latent Poisson random variables  $W_{ijkq}$  with means  $\{\delta \mathbf{A}_i(t_q)\}^{(j,k)}$ .
- The key fact is that the transition probability  $\tilde{\mathbf{P}}_i(u, v)^{(s_0, s_r)}$  is equal to the probability of the event

$$\bigcup_{\text{traj}(s_0, s_1, \dots, s_r)} \left\{ W_{ijkq} > 0 \text{ if there's a transition } j \rightarrow k \text{ at time } t_q \right. \\ \left. \text{and } W_{ijkq} = 0 \text{ otherwise} \right\}.$$

- Thus, maximizing the original likelihood is tantamount to maximizing the likelihood arising from the events of  $W$ 's.

# EM Algorithm

- We can treat  $W_{ijkq}$ 's and  $\mathbf{b}_i$ 's as missing data and apply the EM algorithm for maximizing the likelihood function.
- E-step involves the conditional expectations of  $W_{ijkq}$ 's and functions of  $\mathbf{b}_i$ 's given the observed data, which all have explicit expressions.
- In the M-step,  $\beta_{jk}$ 's can be updated using the one-step Newton-Raphson approach, and  $\lambda_{jkq}$ 's can be updated explicitly.
- Therefore, the EM algorithm is immune to the high-dimensional parameters in NPMLE.

# Asymptotic Properties

- (Consistency) Under some regularity conditions,

$$\|\hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0\| + \sum_{(j,k) \in \mathcal{D}} \|\hat{\Lambda}_{jk} - \Lambda_{0jk}\|_{\infty} \xrightarrow{a.s.} 0.$$

- (Asymptotic normality)  $n^{1/2}(\hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0)$  converges in distribution to a multivariate normal vector with mean zero and a covariance matrix that attains the semiparametric efficiency bound.
- (Variance estimation) The limiting covariance matrix of  $n^{1/2}(\hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0)$  can be consistently estimated by the inverse of

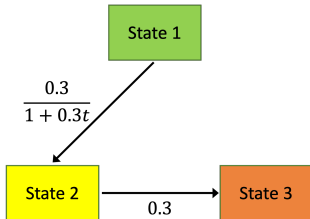
$$n^{-1} \sum_{i=1}^n \left\{ \nabla p l_i(\hat{\boldsymbol{\theta}}) \right\}^{\otimes 2}.$$

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# Simulation Setting

- $X_1 \sim \text{Bernoulli}(0.5)$  and  $X_2 \sim \text{Unif}(0, 1)$
- $b \sim N(0, 0.8)$
- Six potential examination times separated by  $0.05 + \text{Unif}(0, 1)$ ; no examinations beyond  $\tau = 3$ .



# Simulation Results

Table 1: Estimation of regression parameters

	Parameter	Proposed methods				msm package			
		Bias	SE	SEE	CP	Bias	SE	SEE	CP
$n = 400$	$\beta_{121} = 0.5$	0.014	0.265	0.259	95.0	-0.091	0.209	0.207	92.4
	$\beta_{122} = -0.5$	-0.021	0.458	0.448	94.7	0.087	0.363	0.356	94.0
	$\beta_{231} = 0.4$	0.013	0.206	0.198	94.5	-0.078	0.156	0.147	90.4
	$\beta_{232} = 0.2$	0.005	0.350	0.339	94.5	-0.053	0.268	0.254	92.8
	$\sigma^2 = 0.8$	0.060	0.422	0.396	95.1				
$n = 800$	$\beta_{121} = 0.5$	0.010	0.181	0.181	95.4	-0.092	0.145	0.146	90.4
	$\beta_{122} = -0.5$	-0.008	0.315	0.311	95.1	0.095	0.253	0.251	93.1
	$\beta_{231} = 0.4$	0.007	0.139	0.138	95.3	-0.079	0.107	0.104	87.4
	$\beta_{232} = 0.2$	0.006	0.240	0.236	94.6	-0.053	0.187	0.179	92.8
	$\sigma^2 = 0.8$	0.024	0.270	0.263	95.5				
$n = 1600$	$\beta_{121} = 0.5$	0.002	0.127	0.126	94.8	-0.096	0.103	0.103	84.8
	$\beta_{122} = -0.5$	-0.000	0.217	0.216	95.0	0.100	0.176	0.177	91.2
	$\beta_{231} = 0.4$	0.000	0.098	0.096	94.9	-0.080	0.076	0.073	79.7
	$\beta_{232} = 0.2$	-0.002	0.168	0.164	94.7	-0.057	0.132	0.126	91.3
	$\sigma^2 = 0.8$	-0.004	0.181	0.178	95.6				

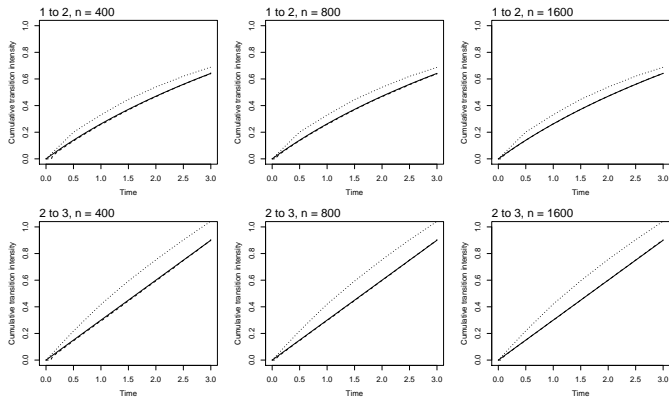


Figure 1: Estimation of cumulative baseline transition intensity functions.

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# ARIC Study

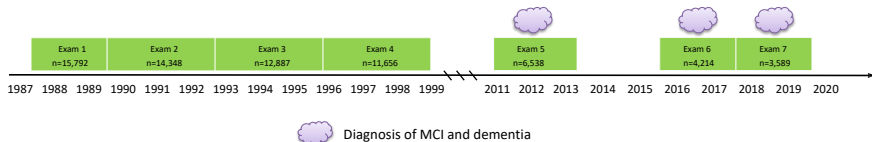


Figure 2: Timeline of the ARIC study.

- 6,407 participants remained after data cleaning
- Median follow-up time: 28.8 years since baseline examination

# Analysis Results

Table 2: Estimation results on the regression parameters in the ARIC study.

Covariate	Normal to MCI			MCI to dementia		
	Estimate	St error	<i>p</i> -value	Estimate	St error	<i>p</i> -value
Age (years)	0.089	0.003	<0.001	0.111	0.006	<0.001
Male	0.319	0.052	<0.001	0.164	0.102	0.108
Advanced education	-0.100	0.053	0.056	-0.616	0.110	<0.001
Diabetes	0.559	0.099	<0.001	0.396	0.165	0.016
Smoker	0.155	0.066	0.019	0.201	0.136	0.138
Body mass index (kg/m <sup>2</sup> )	0.021	0.005	<0.001	0.016	0.009	0.068
Systolic blood pressure (mmHg)	0.005	0.002	0.001	0.006	0.003	0.038
Black, Jackson	-0.001	0.079	0.992	1.469	0.161	<0.001
White, Minneapolis	-0.205	0.072	0.004	0.485	0.162	0.003
White, Washington County	-0.083	0.072	0.252	0.522	0.159	0.001

# Key Findings

- Older people have significantly higher risk of developing both MCI and dementia.
- Advanced education can significantly reduce the risk of progression from MCI to dementia.
- Baseline diabetes occurrence, BMI, and systolic blood pressure are all positively associated with the risk of MCI.
- The variance of the random effect is estimated at 0.928 with a standard error estimator of 0.146, suggesting strong dependence among transitions.

## Extension

- Our methods can be extended to allow a terminal event (e.g., death) that can be exactly observed or right-censored.
- Joint modelling can be used when time-dependent covariates are measured only at a finite number of time points.
- Joint analysis of multiple multi-state disease processes.

**Thank you!**